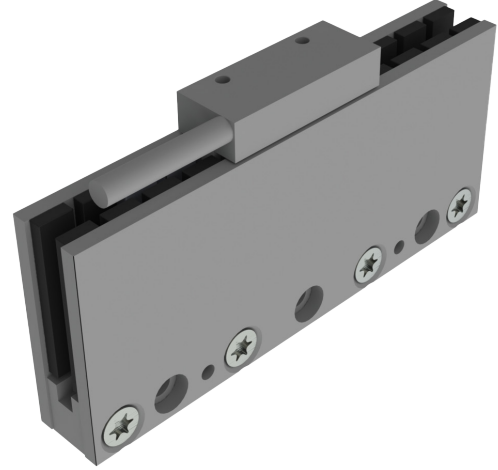


## KMC91S SERIES - IRONLESS LINEAR MOTOR

### DIMENSIONS AND SPECIFICATIONS



Magnet plate dimensions

Code	KMM910066	KMM910099	KMM910264
Le (mm)	66	99	264
M5 bolts	2	3	8
Mass (kg/m)	3,2		
<i>Magnet plates can be butted together.</i>			

		Parameter	Remarks	Sym	Unit	KMC91S	
Performance	Winding type					IU03H	IU07H
	Motor type, max voltage ph-ph					3-phase synchronous Ironless, 45V <sub>ac rms</sub> (60V <sub>dc</sub> )	
	Peak force @ 20°C/s increase	Magnet @ 25°C	F <sub>u</sub>	N	36	72	
	Continuous force*	Coils @ 80°C	F <sub>c</sub>	N	10	20	
	Maximum speed**	@ 60 V	V <sub>max</sub>	m/s	5	5	
	Motor force constant	Mount. sfc. @ 20°C	K	N/A <sub>rms</sub>	11,4	11,4	
Electrical	Motor constant	Coils @ 25°C	S	N <sup>2</sup> /W	9,2	18,3	
	Peak current	Magnet @ 25°C	I <sub>p</sub>	A <sub>rms</sub>	3,1	6,2	
	Maximum continuous current	Coils @ 80°C	I <sub>c</sub>	A <sub>rms</sub>	0,87	1,75	
	Back EMF Phase-Phase <sub>peak</sub>		B <sub>emf</sub>	V/m/s	9,3	9,3	
	Resistance per phase*	Coils @ 25°C ex. cable	R <sub>ph</sub>	Ω	4,7	2,4	
	Induction per phase		L <sub>ph</sub>	mH	0,75	0,38	
Thermal	Electrical time constant*	Coils @ 25°C	T <sub>e</sub>	ms	0,16	0,16	
	Max. continuous power loss	All coils	P <sub>c</sub>	W	13	26	
	Thermal resistance	Coils to mount. sfc.	R <sub>th</sub>	°C/W	3,6	1,8	
	Thermal time constant*	up to 63% max. coiltemp.	T <sub>th</sub>	s	25	25	
Mechanical	Temperature sensor				none	none	
	Coil unit weight	ex. cables	W	kg	0,031	0,062	
	Coil unit length	ex. cables	L	mm	34	67	
	Motor attraction force		F <sub>a</sub>	N	0	0	
	Magnet pitch NN		t	mm	16,5	16,5	
	Cable mass		m	kg/m	0,07	0,07	
	Cable Type (power)	Length 3 m	d	mm (AWG)	4,3 (24)		
	Cable Type (sensor)				N/A		
	Cable life (Power FLEX)***	minimum			15,000,000 cycles		
	Bending radius static	minimum			5x cable diameter		
Bending radius dynamic	minimum			8x cable diameter			

\* These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool.

\*\* Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

\*\*\* Depending on bending radius, velocity and acceleration.

